

2004.1.17

### Contents

Introduction of Smoothing Operation

 Single Plume Transverse Plane
 Linear Smoothing Operation
 Non-Linear Operation
 Conclusion of Smoothing Algorithms

 Number of Separate Images required to get a smoothing Images

 Conclusion of Number of Images

### **Smoothing Operation**

- These algorithms are applied in order to reduce noise and/or to prepare images for further processing such as segmentation.
  - Uniform filter The output image is based on a local averaging of the input filter where all of the values within the filter support have the same weight.

### **Smoothing Operation**

Median filter - The median statistic was described in Section 3.5.2. A median filter is based upon moving a window over an image (as in a convolution) and computing the output pixel as the median value of the brightness's within the input window.



Original Image

RESULTS





Uniform filter

Median filter

### Single Plume Transverse Plane





















10 cm Plume RMS Image



15













### Conclusion of Smoothing Algorithms

- After getting result images, better off smoothing operation
- Filter size (nxn) must be changed as output images
- Linear filter makes simpler image than Non-linear filter's

#### Number of Separate Images required to get a smoothing Images

Compared 1-min data with 2-min data in 5 images(@ 24 sec) -> <u>No Differences</u>



23

### Number of Separate Images required to get a smoothing Images

Compared 5 images(@ 24 sec) with 10 images (@ 12 sec) in 2-min data -> <u>Small differences</u>



#### Conclusion of Number of Images

- If the number of images are not enough, the analysis would be meaningless.
- The more images, The more accuracy
- Should be applied a traditional theory, Nyquist sampling theory.